

# **Two Pathways Lemma and Its Control Applications I**

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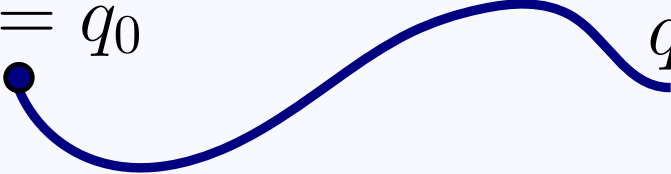
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# Two Pathways Lemma

Consider dynamical system on manifold ( $\alpha \in \mathbb{R}$  - scalar parameter)

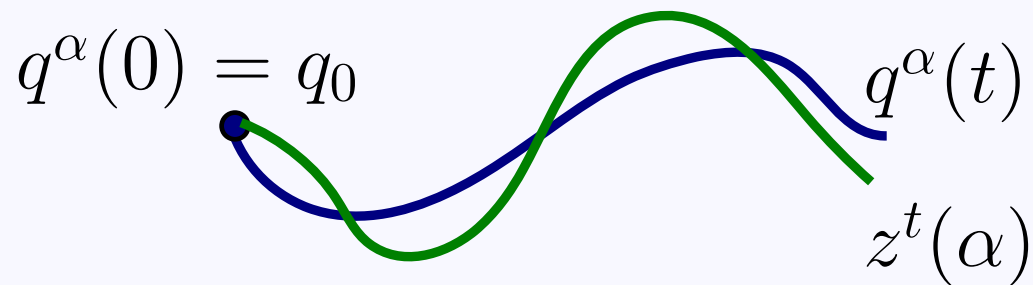
$$\frac{d}{dt}q^\alpha(t) = \alpha V_t(q^\alpha(t)),$$

$$q^\alpha(0) = q_0 \quad \text{---} \quad q^\alpha(t)$$


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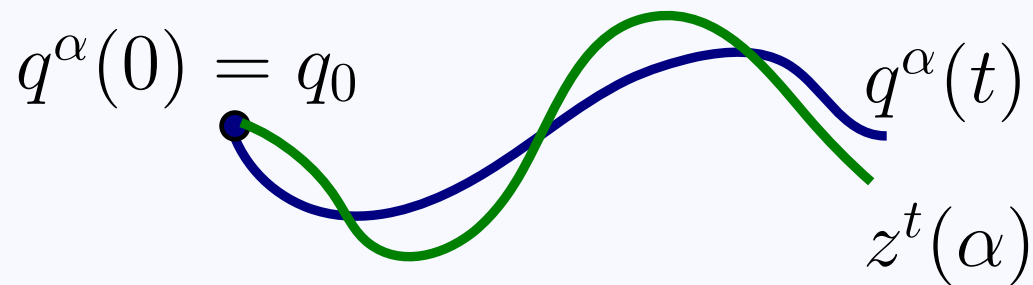


$$\frac{d}{d\alpha} z^t = \sum_{k=1}^{m-1} \alpha^{k-1} \int_0^t dt_1 \int_t^{t_1} dt_2 \int_t^{t_2} dt_3 \dots \int_t^{t_{k-1}} dt_k [V_{t_k}, [\hat{V}_{t_{k-1}}, \dots, [V_{t_2}, V_{t_1}], \dots], ](z^t)$$

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For vector fields  $V(q), W(q)$  with values in tangent space  $T_M(q)$   
Lie bracket

$$[V, W](q) \in T_M(q)$$

# Two Pathways Lemma

If  $M = \mathbb{R}^n$

$$V(q) = \begin{bmatrix} V^1(q) \\ \dots \\ V^n(q) \end{bmatrix}, \quad W(q) = \begin{bmatrix} W^1(q) \\ \dots \\ W^n(q) \end{bmatrix}$$

then

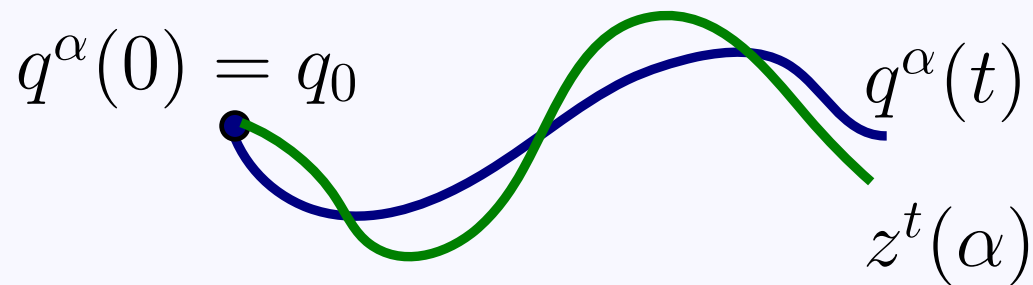
$$[V, W](q) := \begin{bmatrix} \sum_{i=1}^n V^i(q) \frac{\partial W^1}{\partial q^i}(q) - W^i(q) \frac{\partial V^1}{\partial q^i}(q) \\ \dots \\ \sum_{i=1}^n V^i(q) \frac{\partial W^n}{\partial q^i}(q) - W^i(V) \frac{\partial V^n}{\partial q^i}(q) \end{bmatrix}$$

**IMPORTANT:** Lie bracket of vector-fields is again a vector-field

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solution  $q^\alpha(t)$  is approximated by solution  $z^t(\alpha)$

$$\|q^\alpha(t) - z^t(\alpha)\| \quad \text{is small}$$

# Two Pathways Lemma

## TWO PATHWAYS LEMMA:

For any  $q_0 \in M$ , function  $\psi \in C^m(M, E)$  there exists a constant  $K$ ,  $\theta_0$  and neighbourhood  $\mathcal{O}$  of  $q_0$  such that for all sufficiently small  $\alpha$  and  $t \in [0, \theta_0)$  and any solutions  $q^\alpha(t)$  and  $z^t(\alpha)$  with initial conditions  $z^t(0) = q(0) \in \mathcal{O}$

$$\|\psi(q^\alpha(t)) - \psi(z^t(\alpha))\| < K\alpha^m$$

$$\frac{d}{dt}q^\alpha(t) = \alpha V_t(q^\alpha(t))$$

$$\frac{d}{d\alpha} z^t = \sum_{k=1}^{m-1} \alpha^{k-1} \int_0^t dt_1 \int_t^{t_1} dt_2 \int_t^{t_2} dt_3 \dots \int_t^{t_{k-1}} dt_k [V_{t_k}, [\hat{V}_{t_{k-1}}, \dots, [V_{t_2}, V_{t_1}], \dots], ](z^t)$$

## CONTENT

- Prehistory: Derivative of matrix exponential and Wilcox formula



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- Proof of Wilcox formula for linear systems
- Generalization of Wilcox formula for vector-fields on manifolds
- Mathematical tools: Extension of Chronological Calculus by R.Kipka and Yu.L.
- Two Pathways Lemma and Applications

# Derivative of Matrix exponential and Wilcox Formula

Let  $A : \mathbb{X} \rightarrow \mathbb{X}$  be linear bounded operator (or matrix  $A \in \mathbb{R}^{n \times n}$  )  
Operator (matrix) exponential

$$e^A := I + A + \frac{A^2}{2!} + \dots + \frac{A^m}{m!} + \dots = \sum_{k=0}^{\infty} \frac{A^k}{k!}$$

Find derivative of the mapping  $A \rightarrow e^A$

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Find derivative of the mapping  $A \rightarrow e^A$

**F.Schur, H.Poincare**

$$de^A = e^A \frac{I - e^{-\text{ad}(A)}}{\text{ad}(A)}$$

Commutator  $[A, B] := AB - BA$ , linear operator  $\text{ad}(A)$

$$\text{ad}(A)B := [A, B], \quad (\text{ad}(A))^k B := [A, (\text{ad}(A))^{k-1} B],$$

$$k = 1, 2, \dots$$

# Derivative of Matrix exponential and Wilcox Formula

**F.Schur, H.Poincare**

$$de^A = e^A \frac{I - e^{-\text{ad}(A)}}{\text{ad}(A)}$$

Substitute  $x$  by  $\text{ad}(A)$  in

$$\frac{1 - e^{-x}}{x} = \sum_{k=0}^{\infty} \frac{(-1)^k}{(k+1)!} x^k$$

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How to derive formula  $(\square)$

# Derivative of Matrix exponential and Wilcox Formula

In modern textbooks

see **Rossmann**, *Lie Groups*, 2002

they use formula from

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**Wilcox (1967)**

$$\frac{\partial}{\partial \alpha} e^{tH(\alpha)} = \int_0^t e^{(t-s)H(\alpha)} H'(\alpha) e^{sH(\alpha)} ds$$

# Derivative of Matrix exponential and Wilcox Formula

How to prove

**Wilcox (1967)**

$$\frac{\partial}{\partial \alpha} e^{tH(\alpha)} = \int_0^t e^{(t-s)H(\alpha)} H'(\alpha) e^{sH(\alpha)} ds$$

Use formula for differentiation of solution of **LINEAR** differential equation by parameter

Let  $Y_{\Delta\alpha}(t) := e^{tH(\alpha+\Delta\alpha)}$  be a fundamental solution

$$Y'_{\Delta\alpha}(t) = H(\alpha + \Delta\alpha)Y_{\Delta\alpha}(t), \quad Y_{\Delta\alpha}(0) = I$$

and  $Y_0(t) := e^{tH(\alpha)}$  be a solution

$$Y'_0(t) = H(\alpha)Y_0(t), \quad Y_0(0) = I$$

# Derivative of Matrix exponential and Wilcox Formula

Then

$$Y'_{\Delta\alpha}(t) = H(\alpha)Y_{\Delta\alpha}(t) + \Delta H(\Delta\alpha)Y_{\Delta\alpha}(t)$$

where

$$\Delta H(\Delta\alpha) := H(\alpha + \Delta\alpha) - H(\alpha)$$

Use Cauchy formula

$$Y_{\Delta\alpha}(t) = Y_0(t) + \int_0^t e^{(t-s)H(\alpha)} \Delta H(\Delta\alpha) Y_{\Delta\alpha}(s) ds$$

This implies

$$\frac{\partial}{\partial\alpha} e^{tH(\alpha)} = \int_0^t e^{(t-s)H(\alpha)} H'(\alpha) e^{sH(\alpha)} ds$$

Generalization of Wilcox formula for vector fields on manifolds

# Derivative of Matrix exponential and Wilcox Formula

We have

$$\int_0^t e^{(t-s)H(\alpha)} H'(\alpha) e^{sH(\alpha)} ds = e^{tH(\alpha)} \int_0^t e^{-sH(\alpha)} H'(\alpha) e^{sH(\alpha)} ds$$

But

$$\left( e^{tA} B e^{-tA} \right)^{(k)} = e^{tA} (\text{ad}(A))^k B e^{-tA}$$

This implies

$$\int_0^t e^{-sH(\alpha)} H'(\alpha) e^{sH(\alpha)} ds = \int_0^t e^{-s \text{ad}(H(\alpha))} H'(\alpha) ds$$

# Extension of Chronological Calculus by R.Kipka & Yu.L.

$M$  is *Banach manifold* of class  $C^m$  over a Banach space  $E$  is a paracompact Hausdorff space  $M$  along with a collection of coordinate charts  $\{(U_\alpha, \varphi_\alpha) : \alpha \in A\}$ , where  $A$  is an indexing set. Consider dynamical system on  $M$

$$\dot{q} = V_t(q), \quad q(t_0) = q_0.$$

With each nonautonomous vector field  $V_t$  on  $M$ , we associate a local flow

$$P_{t_0, t}(q_0) := q(t; t_0, q_0)$$

Consider the vector space  $C^m(M, E)$  of  $C^m$  functions  $\varphi : M \rightarrow E$ . Then diffeomorphism  $P : M \rightarrow M$  define a linear operator

$$\hat{P}(\varphi) := \varphi \circ P \quad \rightarrow \quad \hat{P}(\varphi)(q) = \varphi(P(q))$$

Vector field  $V$  on  $M$  defines linear operator

$$\widehat{V} : C^m(M, E) \rightarrow C^{m-1}(M, E)$$

$$\widehat{V}(\varphi)(q) := \varphi_*(q)V(q)$$

# Extension of Chronological Calculus by R.Kipka & Yu.L.

Vector field  $V$  on  $M$  defines linear operator

$$\widehat{V} : C^m(M, E) \rightarrow C^{m-1}(M, E)$$

$$\widehat{V}(\varphi)(q) := \varphi_*(q)V(q)$$

Consider operator-valued function  $t \rightarrow A_t$  whose values are linear mappings  $A_t : C^m(M, E) \rightarrow C^p(M, E)$

Then define integral of such function

$$\left( \int_{t_0}^{t_1} A_\tau d\tau \right) (\varphi)(q) := \int_{t_0}^{t_1} A_\tau(\varphi)(q) d\tau$$



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Then we have integral equation

$$\widehat{P}_{t_0,t} = \widehat{Id} + \int_{t_0}^t \widehat{P}_{t_0,\tau} \circ \widehat{V}_\tau d\tau \quad \rightarrow \quad \frac{d}{dt} \widehat{P}_{t_0,t} = \widehat{P}_{t_0,t} \circ \widehat{V}_t, \quad \widehat{P}_{t_0,t_0} = \widehat{Id}.$$

# Extension of Chronological Calculus by R.Kipka & Yu.L.

Integral differential equations

$$\widehat{P}_{t_0,t} = \widehat{Id} + \int_{t_0}^t \widehat{P}_{t_0,\tau} \circ \widehat{V}_\tau d\tau \quad \rightarrow \quad \frac{d}{dt} \widehat{P}_{t_0,t} = \widehat{P}_{t_0,t} \circ \widehat{V}_t, \quad \widehat{P}_{t_0,t_0} = \widehat{Id}.$$

## PRODUCT RULE (Kipka & Yu.L.(2015))

Let

$$\widehat{P}_t = \widehat{P}_{t_0} + \int_{t_0}^t \frac{d}{d\tau} \widehat{P}_\tau d\tau, \quad \widehat{Q}_t = \widehat{Q}_{t_0} + \int_{t_0}^t \frac{d}{d\tau} \widehat{Q}_\tau d\tau,$$

then

$$\int_{t_1}^{t_2} \frac{d}{dt} (\widehat{P}_t \circ \widehat{Q}_t) dt = \int_{t_1}^{t_2} \left( \frac{d}{dt} \widehat{P}_t \circ \widehat{Q}_t + \widehat{P}_t \circ \frac{d}{dt} \widehat{Q}_t \right) dt.$$

# Extension of Chronological Calculus by R.Kipka & Yu.L.

Original Chronological Calculus is due to **Agrachev & Gamkrelidze (mid-1970s)**

Let  $V$  be a vector field and  $F : M \rightarrow M$  be a  $C^m$  diffeomorphism.

Define the operator  $\text{Ad}(\widehat{F}) : \widehat{V} \mapsto \widehat{F} \circ \widehat{V} \circ \widehat{F}^{-1}$ .

Recall Lie bracket  $[V, W]$  of vector fields  $V$  and  $W$  is the vector field whose operator representation has form

$$[\widehat{V}, \widehat{W}] = \widehat{V} \circ \widehat{W} - \widehat{W} \circ \widehat{V}$$

Define an operator  $\text{ad } \widehat{V}_t$  by

$$(\text{ad } \widehat{V}_t) \circ \widehat{W}_t = [\widehat{V}_t, \widehat{W}_t].$$

# Extension of Chronological Calculus by R.Kipka & Yu.L.

$$\text{Ad}(\widehat{F}) : \widehat{V} \mapsto \widehat{F} \circ \widehat{V} \circ \widehat{F}^{-1}$$

$$(\text{ad } \widehat{V}_t) \circ \widehat{W} = [\widehat{V}_t, \widehat{W}].$$

Then important result

$$\frac{d}{dt} \text{Ad}(\widehat{P}_{t_0,t}) \circ \widehat{W} = \text{Ad}(\widehat{P}_{t_0,t}) \circ \text{ad } \widehat{V}_t \circ \widehat{W}$$

# Generalized Wilcox Formula for Manifolds

Consider a parametric family of dynamical systems on Banach manifold  $M$

$$q'(t) = V(t, q(t), \alpha)$$

where  $\alpha$  is a scalar parameter

Let

$$V(t, q, \alpha + \Delta\alpha) = V(t, q, \alpha) + \Delta\alpha W(t, q) + U(t, q, \alpha, \Delta\alpha)$$

where

$$\lim_{\Delta\alpha \rightarrow 0} \frac{1}{\Delta\alpha} \int_{t_1}^{t_2} \|\psi_*(q') U(s, q', \alpha, \Delta\alpha)\| ds$$

# Generalized Wilcox Formula for Manifolds

## Generalized Wilcox Formula

$$\frac{\partial}{\partial \alpha} \hat{P}_t^\alpha = \int_0^t \text{Ad}(\hat{P}_s^\alpha) \circ \frac{\partial}{\partial \alpha} \hat{V}_s^\alpha ds \circ \hat{P}_t^\alpha$$

$$\frac{\partial}{\partial \alpha} \hat{P}_t^\alpha = \hat{P}_t^\alpha \circ \int_0^t \text{Ad}(\hat{P}_{t,s}^\alpha) \circ \frac{\partial}{\partial \alpha} \hat{V}_s^\alpha ds$$

# Generalized Wilcox Formula for Manifolds

## Generalized Wilcox Formula

$$\frac{\partial}{\partial \alpha} \hat{P}_t^\alpha = \int_0^t \text{Ad}(\hat{P}_s^\alpha) \circ \frac{\partial}{\partial \alpha} \hat{V}_s^\alpha ds \circ \hat{P}_t^\alpha$$

$$\frac{\partial}{\partial \alpha} \hat{P}_t^\alpha = \hat{P}_t^\alpha \circ \int_0^t \text{Ad}(\hat{P}_{t,s}^\alpha) \circ \frac{\partial}{\partial \alpha} \hat{V}_s^\alpha ds$$

**PROOF. USE Product Rule**

$$\begin{aligned} \hat{P}_t^{\alpha+\Delta\alpha} \circ \left(\hat{P}_t^\alpha\right)^{-1} - \text{Id} &= \int_0^t \frac{d}{ds} \hat{P}_s^{\alpha+\Delta\alpha} \circ \left(\hat{P}_s^\alpha\right)^{-1} ds = \\ &= \int_0^t \left( \hat{P}_s^{\alpha+\Delta\alpha} \circ \hat{V}_s^{\alpha+\Delta\alpha} \circ \left(\hat{P}_s^\alpha\right)^{-1} - \hat{P}_s^{\alpha+\Delta\alpha} \circ \hat{V}_s^\alpha \left(\hat{P}_s^\alpha\right)^{-1} \right) ds \end{aligned}$$

# Generalized Wilcox Formula for Manifolds

Then we obtain

$$\widehat{P}_t^{\alpha+\Delta\alpha} \circ \left(\widehat{P}_t^\alpha\right)^{-1} - \text{Id} = \Delta\alpha \int_0^t \widehat{P}_s^\alpha \circ \widehat{W}_s \left(\widehat{P}_s^\alpha\right)^{-1} ds \circ \widehat{P}_t^\alpha + \int_0^t \widehat{R}_s ds$$

and

$$\widehat{P}_t^{\alpha+\Delta\alpha} = \widehat{P}_t^\alpha + \Delta\alpha \int_0^t \text{Ad}(\widehat{P}_s^\alpha) \circ \widehat{W}_s ds \circ \widehat{P}_s^\alpha + \hat{o}_t(\Delta\alpha)$$

This implies

$$\frac{\partial}{\partial\alpha} \widehat{P}_t^\alpha = \int_0^t \text{Ad}(\widehat{P}_s^\alpha) \circ \frac{\partial}{\partial\alpha} \widehat{V}_s^\alpha ds \circ \widehat{P}_t^\alpha$$



# Generalized Wilcoxon Formula for Manifolds

Functional-differential equation

$$\frac{\partial}{\partial \alpha} \hat{P}_t^\alpha = \hat{P}_t^\alpha \circ \int_0^t \text{Ad}(\hat{P}_{t,s}^\alpha) \circ \frac{\partial}{\partial \alpha} \hat{V}_s^\alpha ds$$

# Two Pathways Lemma: Approximation Result

Consider differential equation on  $M$

$$\frac{d}{dt} q = \alpha V_t(q)$$

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Consider differential equation on  $M$

$$\frac{d}{dt} q = \alpha V_t(q)$$

Corresponding operator differential equation

$$\frac{d}{dt} \hat{P}_t^\alpha = \hat{P}_t^\alpha \circ \alpha \hat{V}_t$$

# Two Pathways Lemma: Approximation Result

Consider differential equation on  $M$

$$\frac{d}{dt} q = \alpha V_t(q)$$

Corresponding operator differential equation

$$\frac{d}{dt} \hat{P}_t^\alpha = \hat{P}_t^\alpha \circ \alpha \hat{V}_t$$

From generalized Wilcox formula

$$\frac{d}{d\alpha} \hat{P}_t^\alpha = \hat{P}_t^\alpha \circ \int_0^t \text{Ad}(\hat{P}_{t,s}^\alpha) \circ \hat{V}_s ds$$

This is NOT operator differential equation.

This is operator functional-differential equation

# Two Pathways Lemma: Approximation Result

Solution

$$\frac{d}{d\alpha} \widehat{P}_t^\alpha = \widehat{P}_t^\alpha \circ \int_0^t \text{Ad}(\widehat{P}_{t,s}^\alpha) \circ \widehat{V}_s ds$$

can be approximated by solution of operator differential equation

$$\frac{d}{d\alpha} \widehat{Z}_t^\alpha = \widehat{Z}_t^\alpha \circ \widehat{F}_t^\alpha, \quad \widehat{Z}_t^\alpha \Big|_{\alpha=0} = \widehat{Id}$$

where

$$\widehat{F}_t^\alpha := \sum_{k=1}^{m-1} \alpha^{k-1} \int_0^t dt_1 \int_t^{t_1} dt_2 \int_t^{t_2} dt_3 \dots \int_t^{t_{k-1}} dt_k [\widehat{V}_{t_k}, [\widehat{V}_{t_{k-1}}, \dots, [\widehat{V}_{t_2}, \widehat{V}_{t_1}]]]$$

Approximation means

$$\widehat{P}_t^\alpha = \widehat{Z}_t^\alpha + \widehat{O}(\alpha^m),$$

# Two Pathways Lemma: Approximation Result

In the proof to evaluate the vector field

$$\int_0^t \text{Ad}(\hat{P}_{t,t_1}^\alpha) \circ \hat{V}_{t_1} dt_1$$

we use relation

$$\text{Ad}(\hat{P}_{t,t_1}) \circ \hat{W} = \hat{W} + \alpha \int_t^{t_1} dt_2 \text{Ad}(\hat{P}_{t,t_2}) \circ \text{ad}(\hat{V}_{t_2}) \circ \hat{W}$$

# Applications to Asymptotic Behaviour

SMALL TIME

Consider

$$\frac{d}{dt} q(t) = V_t(q(t)), \quad q(0) = q_0$$

# Applications to Asymptotic Behaviour

## SMALL TIME

Consider

$$\frac{d}{dt} q(t) = V_t(q(t)), \quad q(0) = q_0$$

Then solution

$$\frac{d}{d\alpha} z(\alpha) = G_T^\alpha(z(\alpha)), \quad z(0) = q_0$$

$$G_T^\alpha(z) := \sum_{k=1}^{m-1} \alpha^{k-1} \int_0^1 d\tau_1 \int_1^{\tau_1} d\tau_2 \dots \int_1^{\tau_{k-1}} d\tau_k [V_{T\tau_k}, [V_{T\tau_{k-1}}, \dots, [V_{T\tau_2}$$

approximates  $q(T)$  for small  $T$

$$\|\psi(q(T)) - \psi(z(T))\| < KT^m$$



# Applications to Asymptotic Behaviour

## LARGE TIME

Consider

$$\frac{d}{dt} q(t) = V_t(q(t)), \quad q(0) = q_0$$

Then solution

$$\frac{d}{d\alpha} z(\alpha) = G_T^\alpha(z(\alpha)), \quad z(0) = q_0$$

$$\sum_{k=1}^{m-1} \alpha^{k-1} \int_0^{T^2} d\tau_1 \int_{T^2}^{\tau_1} d\tau_2 \dots \int_{T^2}^{\tau_{k-1}} d\tau_k [V_{\tau_k/T}, [V_{\tau_{k-1}/T}, \dots, [V_{\tau_2/T}, V_{\tau_1/T}], \dots]]$$

Approximates  $q(T)$  for large  $T$

$$\|\psi(q(T)) - \psi(z(\alpha_*))\| < K \left(\frac{1}{T}\right)^m$$